

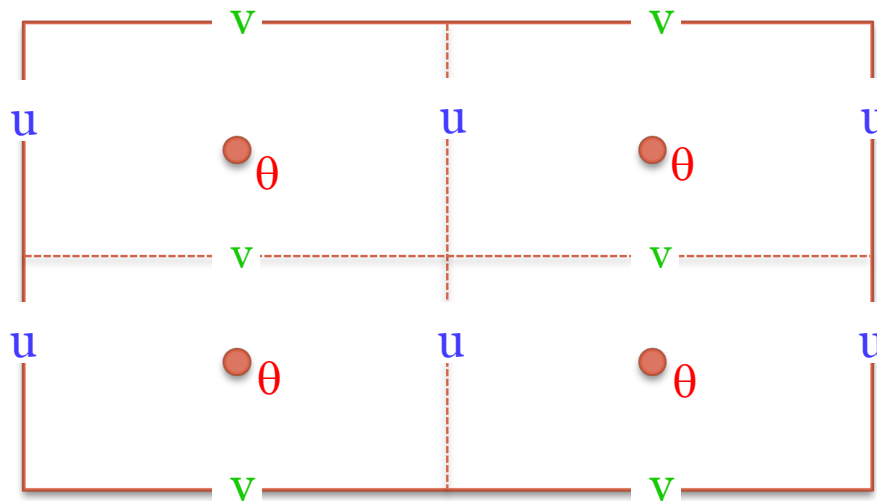
continued:

Computer Program #2

1

TWO-DIMENSIONAL ADVECTION

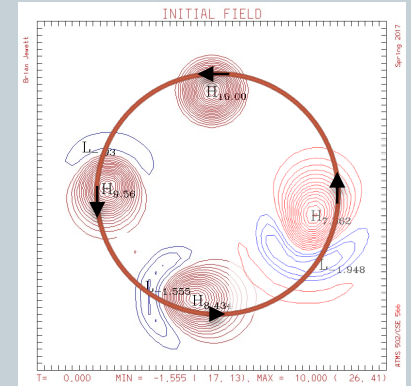
2-D
Staggered
"C-grid"



Program 2 - Review

2

- We are using *circular flow* ...
 - so the easy 'perfect' solution we compare to ... = the **initial condition** (also true in Program 1)
- Arrays etc.
 - Add array: v (the y-velocity)
 - Change arrays: to be **2-D**, $\mathbf{nx} \cdot \mathbf{ny}$
 - Set #ghost points to be: **3** (three points each side of domain)
- Initial condition:
 - $s1$ "cone" • u, v : rotational flow
- Boundary condition: "zero-gradient" (*discuss*)
- Domain: **staggered C-grid in 2-D** (*discuss*)



Program 2 – IC and physical domain

3

IC routine for FORTRAN:

- do j = 1,ny
 - do i = 1,nx
 - ✦ $x = -0.5 + dx * \text{real}(i-1)$
 - ✦ $y = -0.5 + dy * \text{real}(j-1)$
 - ✦ *add code for d = ...*
 - ✦ *add code for s1(i,j) = ...*
- do-loops for u, v:
 - u: i=1,nx+1
 - ✦ $x = (\text{formula above}) - dx/2$
 - v: j = 1,ny+1
 - ✦ $y = (\text{formula above}) - dy/2$

j loop unchanged:
y values unchanged

i loop unchanged:
x values unchanged

IC routine for C:

- for (j=J1; j<=J2; j++) {
 - for (i=I1; i<=I2; i++) {
 - ✦ $x = -0.5 + dx * (\text{float})(i-I1);$
 - ✦ $y = -0.5 + dy * (\text{float})(j-J1);$
 - ✦ *add code for d = ...*
 - ✦ *add code for s1[i][j] = ...*
- for-loops for u, v:
 - u: (i=I1; i<=I2+1; i++)
 - ✦ $x = (\text{formula above}) - dx/2;$
 - v: (j =J1; j<=J2+1; j++)
 - ✦ $y = (\text{formula above}) - dy/2;$

j loop unchanged:
y values unchanged

i loop unchanged:
x values unchanged

Program 2 – boundary conditions (BCs)

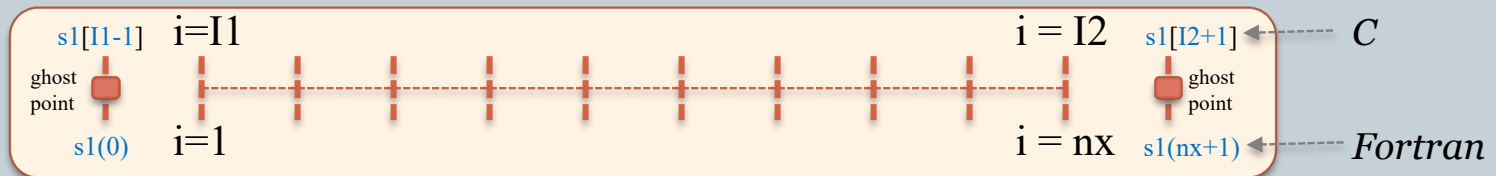
4

FYI ...

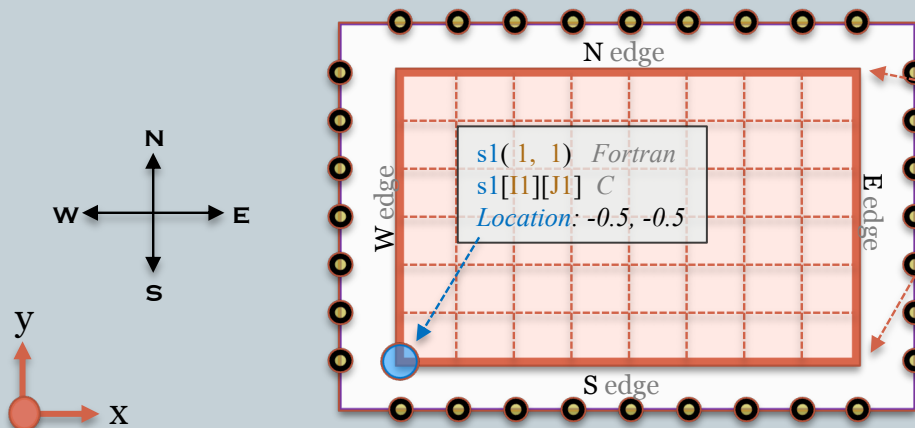


halo regions

- In program 1, our domain was 1-D
 - setting BCs required just *two statements* with *1 ghost point*.



- In program 2, for this 2-D setting ...
 - Our BCs now require *two loops*¹ and *3 ghost points*²



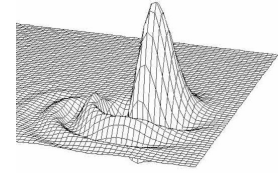
The **physical** domain is shown in light red. In this illustration, it is surrounded by a 1-point-wide halo (ghost zone) region. You need to set all ghost points shown with yellow circles (note our 1-D advection method never uses corner points!)

The easiest way to set these ghost point values is with 2 loops:

1. Loop over all X columns; set ghost points below S edge and above N edge, e.g. loop $i=1, nx$: set $s1(i, 0)$ and $s1(i, ny+1)$
2. Loop over Y rows; set ghost points to left of W edge & right of E edge, e.g.: loop $j=1, ny$: set $s1(0, j)$ and $s1(nx+1, j)$.

This is a 1-ghost-point example. Program #2 needs 3 points!

Program 2 – coding Advection in 2-D



5

• Advection

- I set up temporary 1-D arrays in my 2-D advection routine –

✦ $s1d(-2:nx+3)$, $vel1d(nx+1)$ *no ghost points for U, V !!* until we do nonlinear advection, and u, v are evolved in time, just like $s1()$
for the scalar field *for a velocity (u or v) field*

• Advecting rows (X)

- copy $s1(i,j)$ to $s1d$
- copy $u(i,j)$ to $vel1d$
- pass $s1d$, $vel1d$ to $advect1d()$
 - ✦ $advect1d$ returns $s1d_out$
- copy $s1d_out(i)$ to $s1(i,j)$ *not including² ghost points!!*



within outer j loop, for y

Each bullet is a 1-D loop; I use index i ... for the x-direction. All are within the outer j loop.

Note: in Fortran, can do this w/subscript notation!

• Coding X advection:

- loop over all j rows
 - ✦ loop over all i columns *including¹ ghost points!!*
 - copy $s1(i,j)$ to $s1d(i)$
 - ✦ loop over all i (n_x+1) columns
 - copy $u(i,j)$ to $vel1d(i)$
 - ✦ call $advect1d()$
 - ✦ loop over all i (n_x) columns²
 - copy $s1d_out(i)$ to $s1(i,j)$